

Incorporating Tables into Proofs

by Dale Miller & Vivek Nigam

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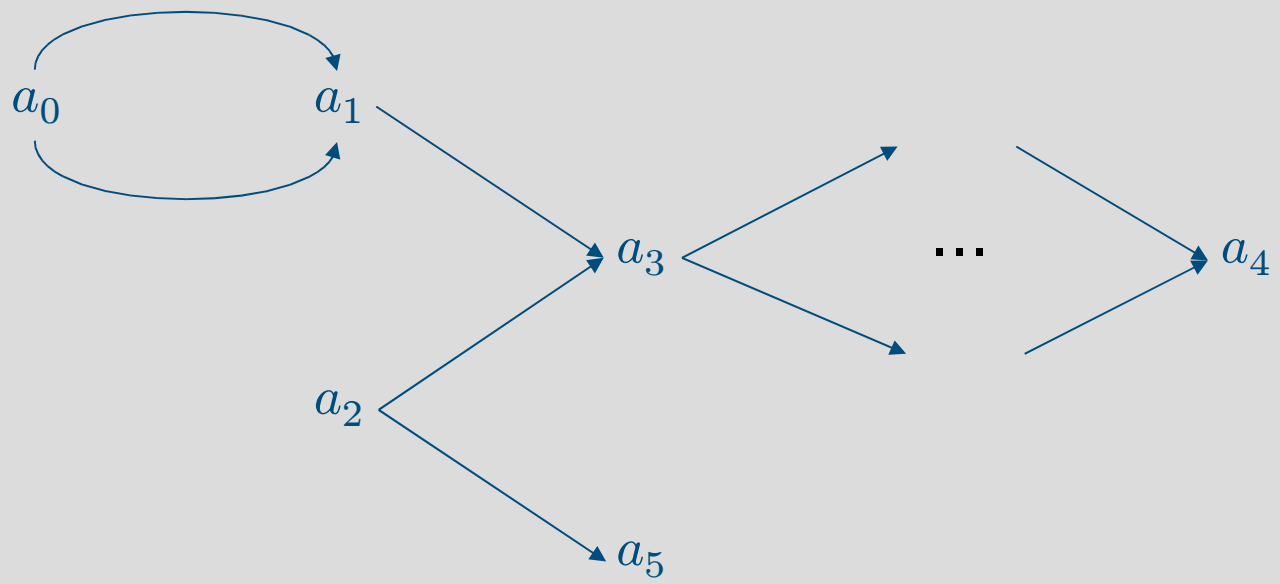
CSL'07

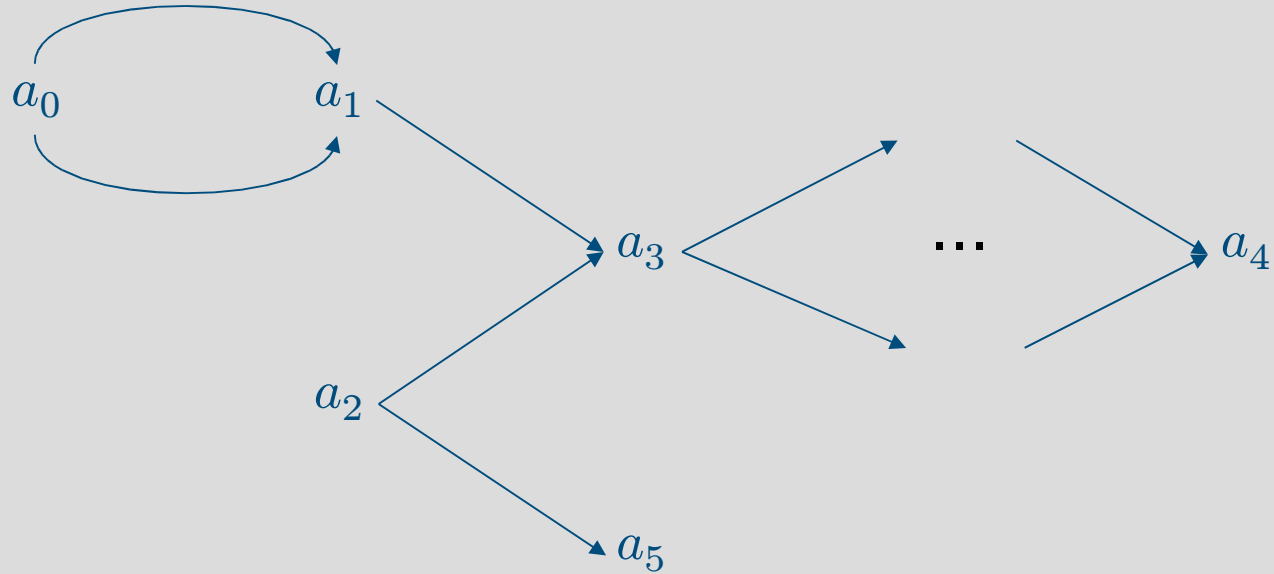
14th of September, 2007

Agenda

■ Motivational Examples

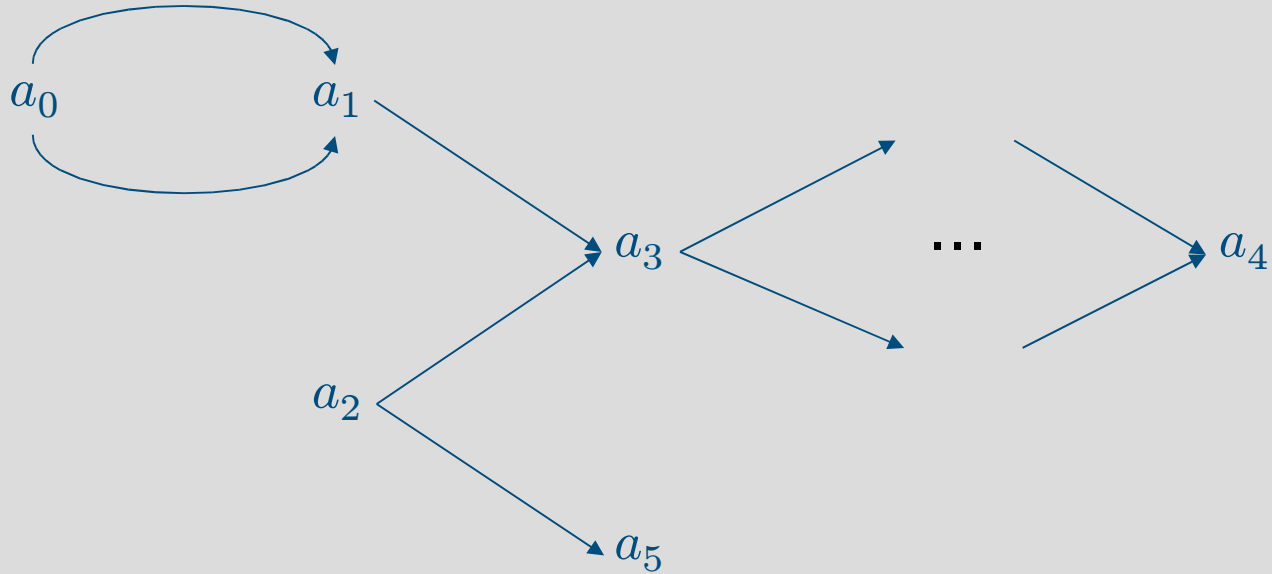
- Focusing
- Finite Successes and Finite Failures
- Applications
- Conclusions and Future Works





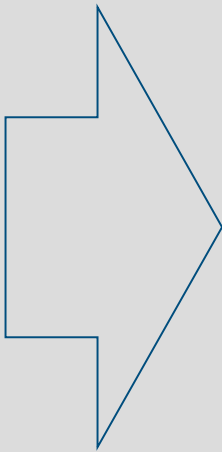
$\forall x(\text{path } x \ x)$
 $\forall x \forall y \forall z (\text{arr } x \ z \wedge \text{path } z \ y \supset \text{path } x \ y)$

$\text{path } a_1 \ a_4 \wedge \text{path } a_2 \ a_4$



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Common Subgoal

$\text{path } a_3 \ a_4$

- In Prolog, this common subgoal is computed twice.

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Another example (without cuts)

- Change to an equivalent goal:

$$A \wedge G \equiv A \wedge (A \supset G)$$

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But we are only increasing non-determinism:

- There are now more proofs for the goal;
- How to give a purely **proof theoretic solution** where common subgoals aren't re-proven.

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■ **Focusing**

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LJF system [Liang & Miller]

$$\frac{[N, \Gamma] \xrightarrow{N} [R]}{[N, \Gamma] \longrightarrow [R]} D_l$$

$$\frac{[\Gamma] \neg P \rightarrow}{[\Gamma] \longrightarrow [P]} D_r$$

$$\frac{[\Gamma], P \longrightarrow [R]}{[\Gamma] \xrightarrow{P} [R]} R_l$$

$$\frac{[\Gamma] \longrightarrow N}{[\Gamma] \neg N \rightarrow} R_r$$

$$\frac{[\Gamma, N_a], \Theta \longrightarrow \mathcal{R}}{[\Gamma], \Theta, N_a \longrightarrow \mathcal{R}} \llbracket_l$$

$$\frac{[\Gamma], \Theta \longrightarrow [P_a]}{[\Gamma], \Theta \longrightarrow P_a} \llbracket_r$$

$$\frac{}{[\Gamma] \xrightarrow{A_n} [A_n]} I_l$$

$$\frac{}{[\Gamma, A_p] \neg A_p \rightarrow} I_r$$

$$\frac{}{[\Gamma], \Theta, \perp \longrightarrow \mathcal{R}} \text{false}$$

$$\frac{[\Gamma], \Theta \longrightarrow \mathcal{R}}{[\Gamma], \Theta, \text{true} \longrightarrow \mathcal{R}} \text{true}_l$$

$$\frac{}{[\Gamma] \neg \text{true} \rightarrow} \text{true}_r$$

$$\frac{[\Gamma], \Theta, A, B \longrightarrow \mathcal{R}}{[\Gamma], \Theta, A \wedge B \longrightarrow \mathcal{R}} \wedge_l$$

$$\frac{[\Gamma] \neg A \rightarrow \quad [\Gamma] \neg B \rightarrow}{[\Gamma] \neg A \wedge B \rightarrow} \wedge_r$$

$$\frac{[\Gamma] \neg A \rightarrow \quad [\Gamma] \xrightarrow{B} [R]}{[\Gamma] \xrightarrow{A \supset B} [R]} \supset_l$$

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$$\frac{[\Gamma], \Theta, A \longrightarrow \mathcal{R}}{[\Gamma], \Theta, \exists y A \longrightarrow \mathcal{R}} \exists_l$$

$$\frac{[\Gamma] \neg A[t/x] \rightarrow}{[\Gamma] \neg \exists x A \rightarrow} \exists_r$$

$$\frac{[\Gamma] \xrightarrow{A[t/x]} [R]}{[\Gamma] \xrightarrow{\forall x A} [R]} \forall_l$$

$$\frac{[\Gamma], \Theta \longrightarrow A}{[\Gamma], \Theta \longrightarrow \forall y A} \forall_r$$

Playing with polarities

$\{a, a \supset b, b \supset c\}$

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b is negative

$$\begin{array}{c}
 \frac{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{b} [b]} \quad I_l}{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{b} [b]} \quad I_l} \supset_l \\
 \frac{[\Gamma] \xrightarrow{a \supset b} [b]}{[\Gamma] \rightarrow [b]} D_l \\
 \frac{[\Gamma] \rightarrow [b]}{[\Gamma] \rightarrow b} \parallel_r \\
 \frac{[\Gamma] \rightarrow b}{[\Gamma] - b \rightarrow} R_r \\
 \frac{\overline{[\Gamma] - b \rightarrow} \quad R_r \quad \overline{[\Gamma] \xrightarrow{c} [c]} \quad I_l}{\overline{[\Gamma] - b \rightarrow} \quad R_r \quad \overline{[\Gamma] \xrightarrow{c} [c]} \quad I_l} \supset_l \\
 \overline{[\Gamma] \xrightarrow{b \supset c} [c]}
 \end{array}$$

b is positive

$$\begin{array}{c}
 \overline{[\Gamma] - a \rightarrow} \quad I_r \\
 \frac{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{c} [c]} \quad I_l}{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{c} [c]} \quad I_l} \supset_l \\
 \frac{[\Gamma, b] \xrightarrow{b \supset c} [c]}{[\Gamma, b] \rightarrow [c]} D_l \\
 \frac{[\Gamma, b] \rightarrow [c]}{[\Gamma], b \rightarrow [c]} \parallel_l \\
 \frac{[\Gamma], b \rightarrow [c]}{[\Gamma] \xrightarrow{b} [c]} R_l \\
 \frac{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{b} [c]} \quad R_l}{\overline{[\Gamma] - a \rightarrow} \quad I_r \quad \overline{[\Gamma] \xrightarrow{b} [c]} \quad R_l} \supset_l \\
 \overline{[\Gamma] \xrightarrow{a \supset b} [c]}
 \end{array}$$

Changing polarities doesn't affect **provability**:

LJF^t

$$\mathcal{P}; \Gamma \longrightarrow G$$

$$\frac{\mathcal{P}; [\Gamma] \longrightarrow L_1 \quad \dots \quad \mathcal{P}; [\Gamma] \longrightarrow L_n \quad \mathcal{P} \cup \Delta_P; [\Gamma \cup \Delta_L] \longrightarrow [R]}{\mathcal{P}; [\Gamma] \longrightarrow [R]} \text{mc.}$$

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Proposition: LJF^t is sound and complete w.r.t LJF

- The idea is to assign at the base of the tree **negative polarity** to all atoms, and then use the mulitcut rule to change the polarity of some atoms to **positive polarity**.

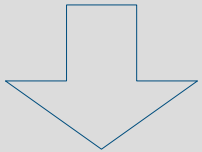
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A **Table is a partially ordered set of lemmas, and it specifies a multicut derivation**

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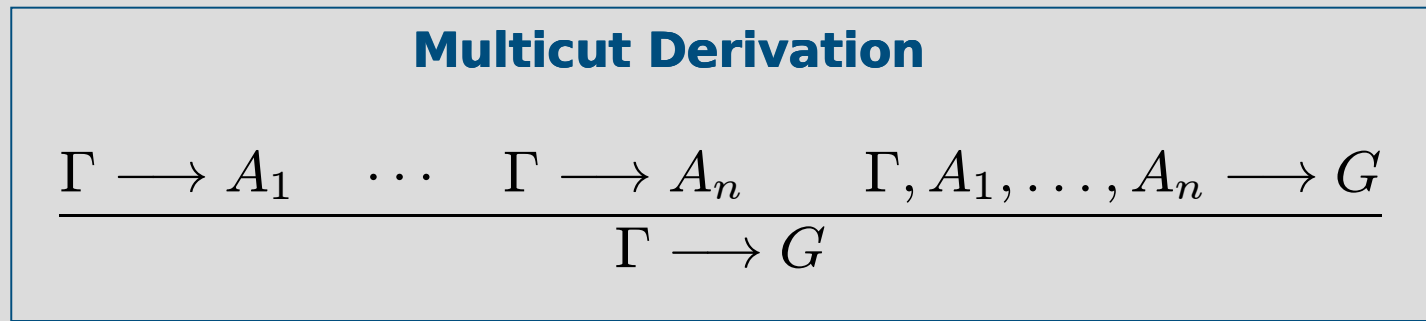
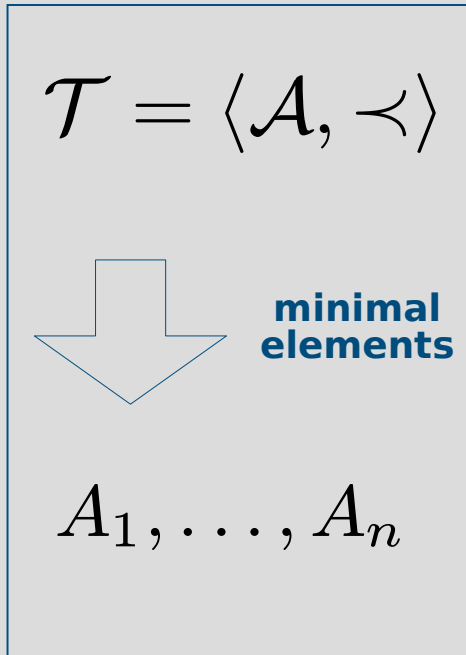
$$\mathcal{T} = \langle \mathcal{A}, \prec \rangle$$



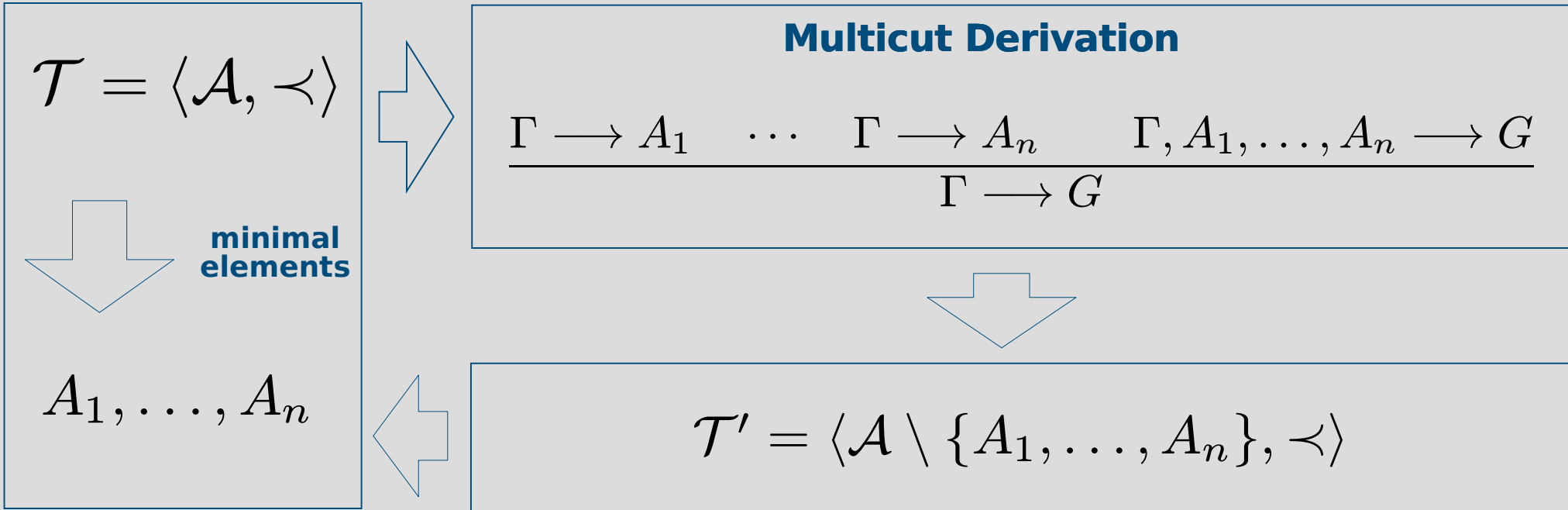
**minimal
elements**

$$A_1, \dots, A_n$$

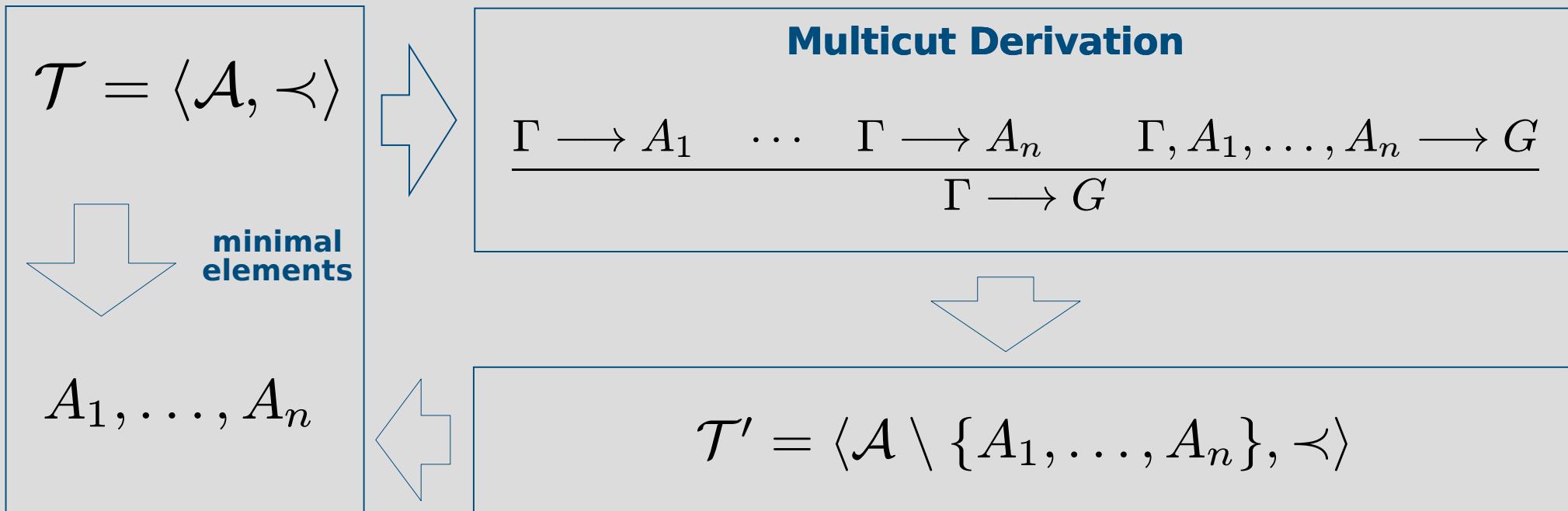
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Where do tables come from:

- Lemmas in an Interactive Theorem Prover – Boyer & Moore;
- Logic Programming – *Tabled Deduction*;
- Extracted from an known proof (e.g. depth first traversal) - *Proof Carrying Code*;

Consider: **Horn Theory** and Tables composed only of **atoms**

Proposition: Let Γ be a set of Horn clauses, $A \in \mathcal{P} \cap \Gamma$, and Ξ be an arbitrary LJF^t proof tree for $\mathcal{P}; [\Gamma] -_G \rightarrow$. Then every occurrence of a sequent with right-hand side the atom A is the conclusion of an I_r^t rule.

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Returning to the Examples

$$\begin{array}{c}
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] \xrightarrow{\text{arr}_{a_1 \ a_3}} [\text{arra}_1 \ a_3]} I_l^t \\
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] \longrightarrow [\text{arra}_1 \ a_3]} D_l^t \\
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] - \text{arr}_{a_1 \ a_3} \longrightarrow} R_r^t \\
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] - \text{path } a_3 \ a_4 \longrightarrow} I_r^t \\
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] - \text{arr}_{a_1 \ a_3} \wedge \text{path } a_3 \ a_4 \longrightarrow} D_l^t, \forall_l^t, \forall_l^t, \forall_l^t, \supset_l^t \\
 \frac{}{\text{path } a_3 \ a_4; [\Gamma, \text{path } a_3 \ a_4] \longrightarrow [\text{path } a_1 \ a_4]} \wedge_r^t
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$$\frac{\Gamma \longrightarrow A \quad \Gamma \longrightarrow G}{\Gamma \longrightarrow A \wedge G} \implies \frac{\mathcal{P}; [\Gamma] \longrightarrow [A] \quad \mathcal{P} \cup \{A\}; [\Gamma, A] \longrightarrow [A \wedge G]}{\mathcal{P}; [\Gamma] \longrightarrow [A \wedge G]} \text{mc.}$$

Consider: **Horn Theory** and Tables composed by **literals**

A well studied way to handle **negation-as-finite-failure** in sequent calculus is with the use of definitions (fixed points):

$$\frac{\{\mathcal{P}; [\Gamma\theta], \Theta\theta, B\theta \longrightarrow \mathcal{R}\theta \mid \theta = mgu(H, A) \text{ for some clause } H \stackrel{\Delta}{=} B\}}{\mathcal{P}; [\Gamma], \Theta, A \longrightarrow \mathcal{R}} \text{Def}_l, A \notin \mathcal{P}$$

$$\frac{\mathcal{P}; [\Gamma] -_{B\theta} \longrightarrow}{\mathcal{P}; [\Gamma] -_{A_n} \longrightarrow} \text{Def}_r, A_n \notin \mathcal{P}, \text{ where } H \stackrel{\Delta}{=} B, \text{ and } H\theta = A_n$$

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Proposition: Let Γ be a set of literals built on positive polarity atoms, and let $L \in \Gamma$. If Ξ is proof of $\mathcal{P}; [\Gamma] -_{\mathcal{G}} \longrightarrow$ then all occurrences of sequents in Ξ that have L as their right-focus formula are the conclusion of a proof with Def_r -depth at most 1.

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Declarative Interpretation for *Tabled Deduction*

Both finite successes and finite failures are stored in a table, and if:

- There is another attempt to prove a **finite success**, the proof search ends with success;
 - **Follows from the previous result;**

Declarative Interpretation for *Tabled Deduction*

Both finite successes and finite failures are stored in a table, and if:

- There is another attempt to prove a **finite success**, the proof search ends with success;
 - **Follows from the previous result;**
- There is another attempt to prove a **finite failure**, this proof search fails immediately
 - **Follows from the following result:**

Proposition: Let A be an atom such that $\Gamma \longrightarrow A$ is not provable and let $A \in \mathcal{P}$. Let Ξ be an arbitrary $LJF^{\Delta t}$ derivation for $\mathcal{P}; [\Gamma] -_G \rightarrow$. Then all sequents in Ξ with right-hand side A are open leaves.

Proof Carrying Code – Tables as Proof Objects

If tables are used as **proof objects** they seem to enjoy the following crucial properties:

- Small;
- Easy to Check;
- Flexible.

Proposition: Let Ξ be a *LJF* proof of $\Gamma \longrightarrow G$ and let \mathcal{T} be a table obtained from Ξ using a postorder traversal. There exists a proof for $mcd(\mathcal{T}, [.] \Gamma \longrightarrow G)$ such that all of its added subproofs have decide-depth of one or less.

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Conclusions and Future Works

- **Extend these results to stronger logics**

- Hereditary Harrop Formulas;
- mu-Mall (Sequent calculus with Induction and Co-induction) [Baelde & Miller – LPAR'07];
- Experiments.

- **Investigate connections with Interactive Theorem Proving**

- Use a sequence of lemmas to prove a theorem in such a way that the gaps between them are “easy” to be found.